

PROBLEM 1

Data summary

Applied force F

rectangular pulse with duration $T_A = 80\text{ms}$

Piezoelectric force sensor

$A_q = 5\text{pC/N}$ force-to-charge conversion

$C_s = 500\text{pF}$ total capacitance of sensor and connected circuit

Preamplifier

Input resistance R_{iA} very high $> 500\text{ M}\Omega$, to be treated as ∞

$f_{pa} = 20\text{MHz}$ band limit

$$\sqrt{S_v} = 4\text{nV} / \sqrt{\text{Hz}} \quad \text{wide-band (unilateral)}$$

$$\sqrt{S_i} = 0,01\text{pA} / \sqrt{\text{Hz}} \quad \text{wide-band (unilateral);}$$

where stated, consider in S_i and in S_v also a $1/f$ component with corner frequency $f_c = 500\text{ Hz}$

A) Optimum filtering

Applied force F

piezoelectric charge $Q = A_Q F$

Preamp input signal $V_s = \frac{Q}{C_s}$

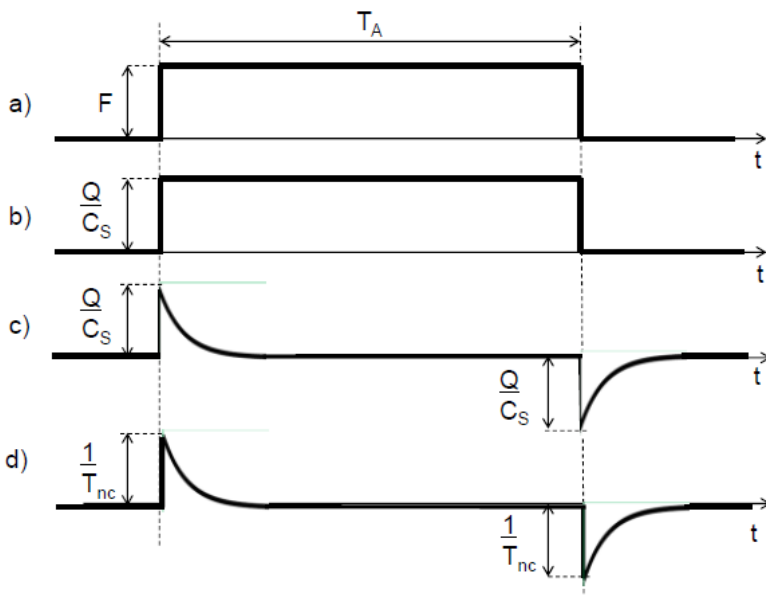


Fig. 1 a) Force applied to the piezoelectric sensor
b) Sensor voltage signal

- c) output voltage signal of the whitening filter
- d) weighting function of the matched filter

The noise at the preamp output is

$$S_S = S_v + \frac{S_i}{\omega^2 C_s^2} = S_v \frac{1 + \omega^2 \frac{C_s^2 S_v}{S_i}}{\omega^2 \frac{C_s^2 S_v}{S_i}} = S_v \frac{1 + \omega^2 T_{nc}^2}{\omega^2 T_{nc}^2}$$

the characteristic time constant is $T_{nc} = \frac{C_s S_v^{1/2}}{S_i^{1/2}} = 200 \mu s$

The noise is NOT WHITE, therefore:

Optimum Filter = Whitening Filter plus Matched Filter.

Whitening Filter $H_B(f)$

It is a constant-parameter linear filter applied at the preamp output: a CR differentiator with time constant $T_B = T_{nc}$

$$|H_B|^2 = \frac{\omega^2 T_B^2}{1 + \omega^2 T_B^2} = \frac{\omega^2 T_{nc}^2}{1 + \omega^2 T_{nc}^2}$$

H_B output: white noise

$$S_B = S_S |H_B|^2 = S_v$$

and signal composed by two exponential pulses (Fig.1), a positive one at $t = 0$ force start) and a negative one at $t = T_A$ (force end)

$$v_B(t) = \frac{Q}{C_s} \left[1(t) \cdot e^{-\frac{t}{T_{nc}}} - 1(t - T_A) \cdot e^{-\frac{t - T_A}{T_{nc}}} \right]$$

Matched Filter:

its weighting function w_M has shape identical to the signal v_B (Fig.1)

$$w_M(\alpha) = \frac{1}{T_{nc}} \left[1(\alpha) \cdot e^{-\frac{\alpha}{T_{nc}}} - 1(\alpha - T_A) \cdot e^{-\frac{\alpha - T_A}{T_{nc}}} \right]$$

Since $T_{nc} \ll T_B$ the two exponential pulses are well separated (the overlap is negligible) and calculations are simplified. At the matched filter output

signal $V_M = \int_0^{\infty} v_B(\alpha) w_M(\alpha) d\alpha$

noise
$$\overline{v_{n,M}^2} = \int_{-\infty}^{\infty} S_{V,b} \delta(\tau) k_{ww,M}(\tau) d\tau = S_{V,b} k_{ww,M}(0) = \frac{S_v}{2} k_{ww,M}(0)$$

In the case of a simple step force (force applied and maintained indefinitely) the output signal $v_B(\alpha)$ of the whitening filter and the corresponding weighting function $w_M(\alpha)$ would have just a positive exponential pulse and we would have

signal
$$V_{M,u} = \frac{Q}{2C_s}$$

noise
$$\sqrt{v_{n,Mu}^2} = \frac{S_v^{1/2}}{\sqrt{4T_{nc}}}$$

therefore
$$\left(\frac{S}{N}\right)_{Mu} = \frac{Q}{C_s} \cdot \frac{1}{\frac{S_v^{1/2}}{\sqrt{4T_{nc}}}}$$

In the actual case, the applied force has finite duration T_A (rectangular pulse) so that $v_B(\alpha)$ and $w_M(\alpha)$ include two well separate exponential pulses. Therefore, the signal amplitude and the noise mean square value are greater by a factor 2 than the case of simple step force so that S/N is improved by a factor $\sqrt{2}$

signal
$$V_{M,r} = 2V_{M,u} = \frac{Q}{C_s}$$

noise
$$\sqrt{v_{n,Mr}^2} = \sqrt{2v_{n,Mu}^2} = \frac{S_v^{1/2}}{\sqrt{2T_{nc}}}$$

therefore
$$\left(\frac{S}{N}\right)_{Mr} = \frac{Q}{C_s} \cdot \frac{1}{\frac{S_v^{1/2}}{\sqrt{2T_{nc}}}} \cdot \sqrt{2}$$

The minimum measurable voltage signal thus is

$$V_{M,r \min} = \sqrt{v_{n,Mr}^2} = \frac{S_v^{1/2}}{\sqrt{2T_{nc}}} = 200nV$$

It corresponds to a minimum measurable piezoelectric charge

$$Q_{M,r \min} = C_s V_{M,r \min} = 10^{-16} C$$

and to a minimum measurable force

$$F_{M,rmin} = \frac{Q_{min}}{A_Q} = 20\mu N$$

B) Approximation of the optimum filtering with a Gated Integrator

A weighting function that approximates the optimum filtering can be obtained with a gated integrator (GI) that weights in sequence the two exponential pulses of the signal v_B and then combines the first and the second (negative) measurement.

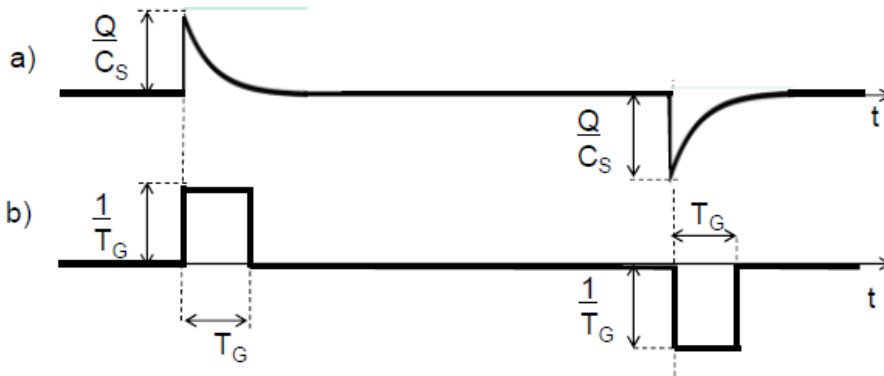


Fig. 2 a) Voltage signal at the whitening filter output
 b) weighting function of the Gated Integrator

The result depends on the selected gating time T_G . It is quite evident that for approximating the optimum weighting the duration T_G must be comparable with the noise characteristic time constant T_{nc} and it is possible to find out the T_G value that gives the best result.

Also employing a GI we can gain a better insight by first considering the case of a simple step force and then that of rectangular force with finite duration T_A .

Denoting by w_G the weighting function for the filtering by a GI, we have at the GI output

signal
$$V_G = \int_0^{\infty} v_B(\alpha) w_G(\alpha) d\alpha$$

noise
$$\sqrt{v_{n,G}^2} = \int_{-\infty}^{\infty} S_{V,bil} \delta(\tau) k_{ww,G}(\tau) d\tau = S_{V,bil} k_{ww,G}(0) = \frac{S_V}{2} k_{ww,G}(0)$$

With a simple step force, considering a GI with normalized weight

$$w_G(\alpha) = \frac{1}{T_G} \quad \text{for } 0 < \alpha < T_G \quad \text{and elsewhere } w_G(\alpha) = 0$$

We get

signal
$$V_{Gu} = \frac{Q}{C_s} \cdot \frac{1 - e^{-T_G/T_{nc}}}{\frac{T_G}{T_{nc}}}$$

noise
$$\sqrt{V_{n,Gu}^2} = \frac{S_v^{1/2}}{\sqrt{2T_G}} = \frac{S_v^{1/2}}{\sqrt{2T_{nc}}} \sqrt{T_{nc}}$$

therefore
$$\left(\frac{S}{N}\right)_{Gu} = \frac{Q}{C_s} \cdot \frac{1}{\frac{S_v^{1/2}}{\sqrt{T_{nc}}}} \cdot \sqrt{2} \cdot \frac{1 - e^{-T_G/T_{nc}}}{\sqrt{T_{nc}}}$$

that is, by denoting $x = \frac{T_G}{T_{nc}}$

$$\left(\frac{S}{N}\right)_{Gu} = \frac{Q}{C_s} \cdot \frac{1}{\frac{S_v^{1/2}}{\sqrt{T_{nc}}}} \cdot \sqrt{2} \cdot \frac{1 - e^{-x}}{\sqrt{x}} = \left(\frac{S}{N}\right)_{Mu} \cdot \sqrt{2} \cdot \frac{1 - e^{-x}}{\sqrt{x}}$$

the function $g(x) = \frac{1 - e^{-x}}{\sqrt{x}}$ attains a maximum $g_{\max} \approx 0,638$ for $x \approx 1,25$; therefore, at the

maximum we get $\sqrt{2}g_{\max} = 0,9$. In conclusion: with $T_G \approx 1,25 T_{nc} \approx 250 \mu s$ we get

$$\left(\frac{S}{N}\right)_{Gu} = \frac{Q}{C_s} \cdot \frac{1}{\frac{S_v^{1/2}}{\sqrt{T_{nc}}}} \cdot 0,9 \cong \left(\frac{S}{N}\right)_{Mu} \cdot 0,9$$

That is, a result only 10% lower than that given by the optimum filter. We may further note that the setting of T_G is not critical because the maximum of $g(x)$ is not narrow: between $x=1$ and $x=1,6$ the function $g(x)$ varies just by a few %.

In the case of force applied for a finite duration T_A , $v_B(\alpha)$ has two well separated exponential pulses and $w_G(\alpha)$ has correspondingly two rectangular pulses of duration T_G . With respect to the case of simple step force, the signal value and the mean square noise value are increased by a factor 2 and hence the S/N by a factor $\sqrt{2}$.

signal
$$V_{Gr} = \frac{Q}{C_s} \cdot 2 \frac{1 - e^{-T_G/T_{nc}}}{\frac{T_G}{T_{nc}}}$$

noise
$$\sqrt{v_{n,Gr}^2} = \frac{S_v^{1/2}}{\sqrt{T_G}} = \frac{S_v^{1/2}}{\sqrt{T_{nc}}} \sqrt{\frac{T_{nc}}{T_G}} = 253 \text{ nV}$$

hence
$$\left(\frac{S}{N}\right)_{Gr} = \frac{Q}{C_s} \cdot \frac{1}{\frac{S_v^{1/2}}{\sqrt{T_{nc}}}} \cdot 2 \cdot \frac{1 - e^{-T_G/T_{nc}}}{\sqrt{\frac{T_G}{T_{nc}}}} = \left(\frac{S}{N}\right)_{Mr} \sqrt{2} \cdot \frac{1 - e^{-T_G/T_{nc}}}{\sqrt{\frac{T_G}{T_{nc}}}}$$

The maximum is attained with $T_G/T_{nc} \approx 1,25$, which gives

$$\left(\frac{S}{N}\right)_{Gr} \cong \left(\frac{S}{N}\right)_{Mr} \cdot 0,9$$

thus a minimum measurable piezoelectric charge

$$Q_{G,r\min} = \frac{Q_{M,r\min}}{0,9} = 1,11 \cdot 10^{-16} \text{ C}$$

and a corresponding minimum measurable force

$$F_{g,r\min} = \frac{F_{M,r\min}}{0,9} = 22 \mu\text{N}$$

C) Effect of the 1/f noise

C1) Current noise

$$S_{if} = \frac{S_i f_c}{f}$$

It is filtered (integrated) by the capacitance C_s and transformed in voltage noise spectrum

$$S_{if} \frac{1}{\omega^2 C_s^2}$$

The noise whitening filter then cancels the pole at $\omega=0$ and replaces it with a pole at $\omega_{nc}=1/T_{nc}$

$$S_{if} \frac{1}{\omega^2 C_s^2} \frac{\omega^2 T_{nc}^2}{1 + \omega^2 T_{nc}^2} = S_{if} \frac{T_{nc}^2}{C_s^2} \frac{1}{1 + \omega^2 T_{nc}^2} = S_i \frac{f_c T_{nc}^2}{f C_s^2} \frac{1}{1 + \omega^2 T_{nc}^2}$$

Taking into account the equation $T_{nc} = \frac{C_s S_v^{1/2}}{S_i^{1/2}}$ the output of the noise whitening filter is

$$S_i \frac{f_c T_{nc}^2}{f C_s^2} \frac{1}{1 + \omega^2 T_{nc}^2} = S_i \frac{f_c S_v}{f S_i} \frac{1}{1 + \omega^2 T_{nc}^2} = S_v \frac{f_c}{f} \frac{1}{1 + \omega^2 T_{nc}^2} = S_v \frac{f_c}{f} \frac{1}{1 + (2\pi f)^2 T_{nc}^2}$$

We recognize that the noise brought to the output of the whitening filter by the current 1/f noise is equal to the voltage 1/f spectrum filtered by a low-pass filter with a simple pole at $\omega_{nc}=1/T_{nc}$

$$S_V \frac{f_c}{f} \frac{1}{1+(2\pi f)^2 T_{nc}^2}$$

The processing carried out with the Gated Integrator and illustrated in Sec.B performs

- A low-pass filtering with band-limit frequency $1/2T_G$ (integration over the gate time T_G)
- A high-pass filtering with band-limit frequency $1/T_A$ (subtraction of two GI operations separated by a time interval T_A)

The low-pass filtering brings the upper frequency limit down to $f_s \approx 1/2T_G$, which by selecting $T_G \approx 1,25T_{nc}$ is set to $f_s \approx 1/2,5 T_{nc} = 2\text{kHz}$.

The high-pass filtering sets a lower band-limit at $f_{ii} \approx 1/T_A \approx 12,5\text{Hz}$.

This 1/f noise contribution can thus be evaluated with the sharp-cut in frequency

$$\sqrt{v_{n,Gr}^2} = \sqrt{S_v f_c} \cdot \sqrt{\ln\left(\frac{f_s}{f_{ii}}\right)} \approx \sqrt{S_v f_c} \cdot \sqrt{\ln\left(\frac{T_A}{2,5T_{nc}}\right)} = 201 \text{ nV}$$

and turns out to be tolerable, since it is slightly lower than the contribution of the white noise components

$$\sqrt{v_{n,Gr}^2} = \frac{S_v^{1/2}}{\sqrt{T_G}} = \frac{S_v^{1/2}}{\sqrt{1,25T_{nc}}} = 253 \text{ nV}$$

C1) Voltage noise

$$S_{Vf} = \frac{S_v f_c}{f}$$

For the voltage noise 1/f component

- The sensor capacitance C_S does not introduce any filtering
- The noise whitening filter gives a high-pass filtering which attenuates the spectrum in the low frequency region. It enforces to the voltage 1/f noise component a lower band limit $f_{iV} \approx 1/2\pi T_{nc} \approx 800\text{Hz}$ much stronger than that enforced to the current 1/f noise component $f_{ii} \approx 1/T_A \approx 12,5\text{Hz}$

$$S_{Vf} \frac{\omega^2 T_{nc}^2}{1 + \omega^2 T_{nc}^2} = S_v \frac{f_c}{f} \frac{(2\pi f)^2 T_{nc}^2}{1 + (2\pi f)^2 T_{nc}^2}$$

- The integration carried out with the Gated Integrator (illustrated in Sec.B) attenuates the spectrum in the high frequency region and sets an upper bandlimit $f_s \approx 1/2T_G$.
- The double measurement by the GI sets also the high-pass band-limit $f_{hi} \approx 1/T_A \approx 12,5\text{Hz}$ as for the current $1/f$ noise component, which however in this case has negligible effect since it is at much lower frequency than the high-pass band-limit produced by the whitening filter.

In summary, the contributions of the voltage $1/f$ component and of the current $1/f$ noise component

are computed with the same spectral density $S_{vf} = \frac{S_v f_c}{f}$ filtered with the same upper bandlimit

$f_s \approx 1/2T_G$, but with a much higher band-limit at low-frequency for the voltage noise. We can conclude that the contribution of the voltage $1/f$ noise is much lower than that of the current $1/f$ noise and is therefore negligible